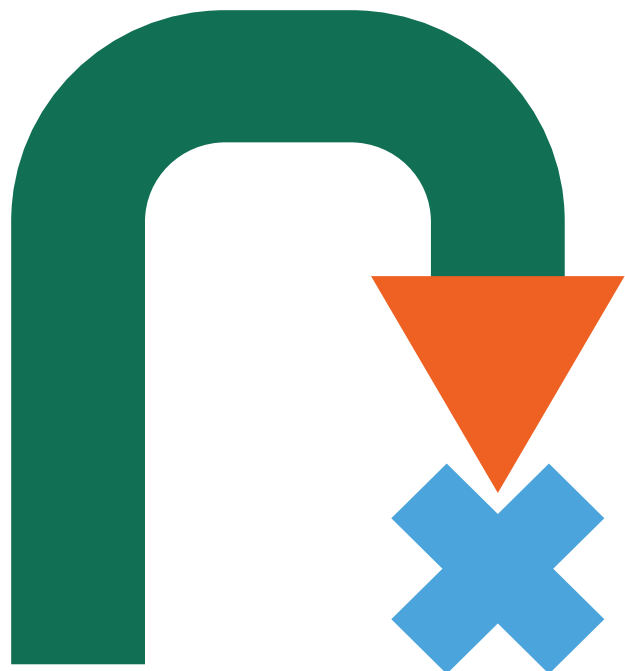


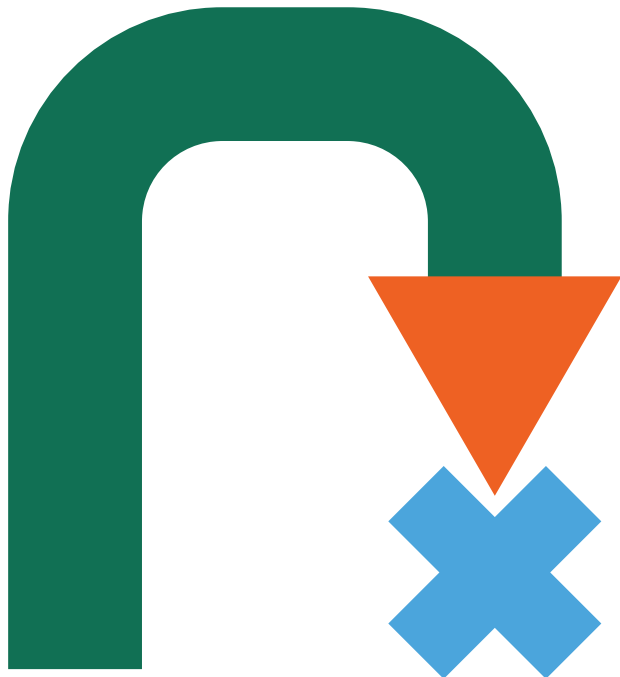
90° Pivot Right Finish Left



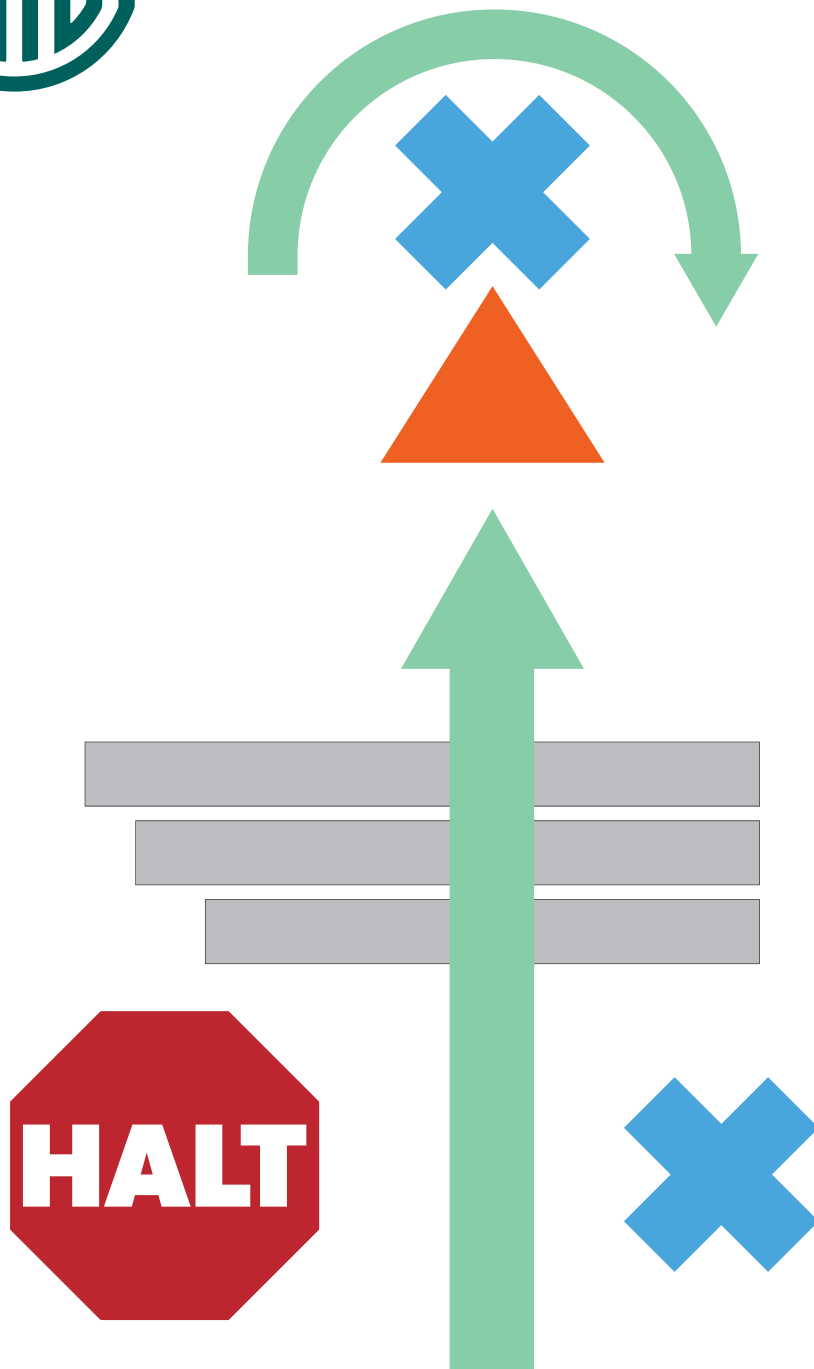
Call Dog Front



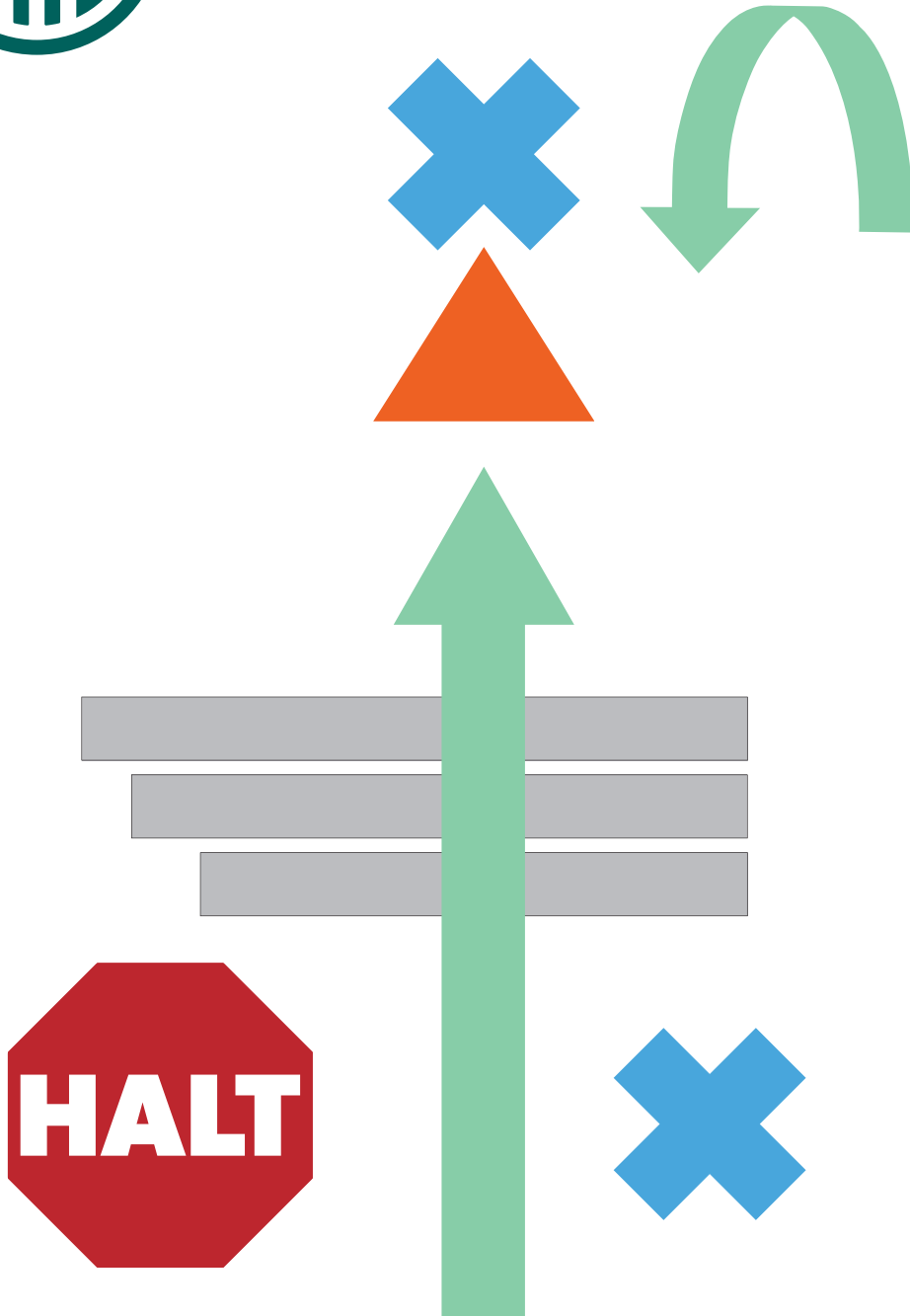
90° Pivot Left Finish Right



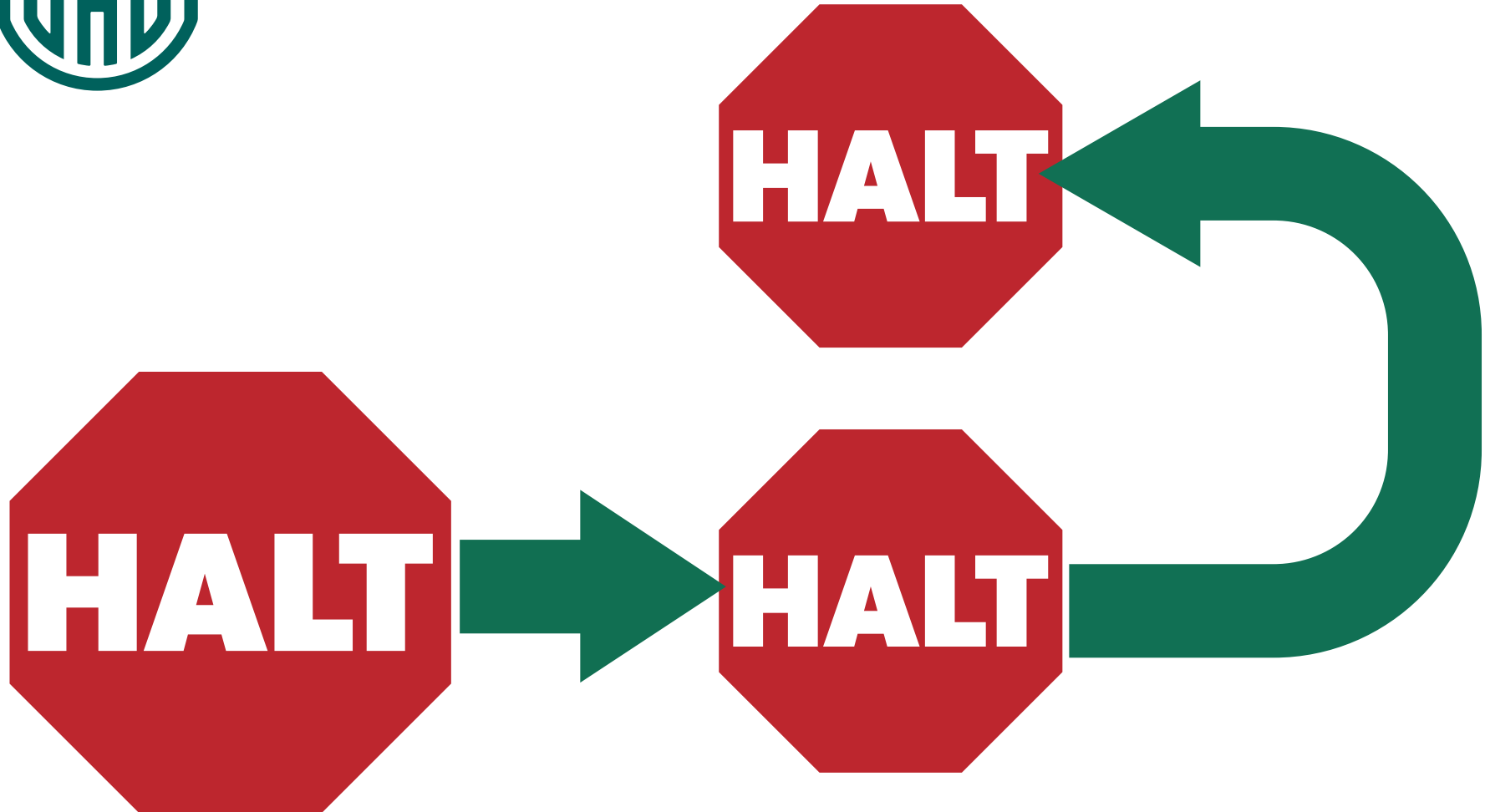
Call Dog Front



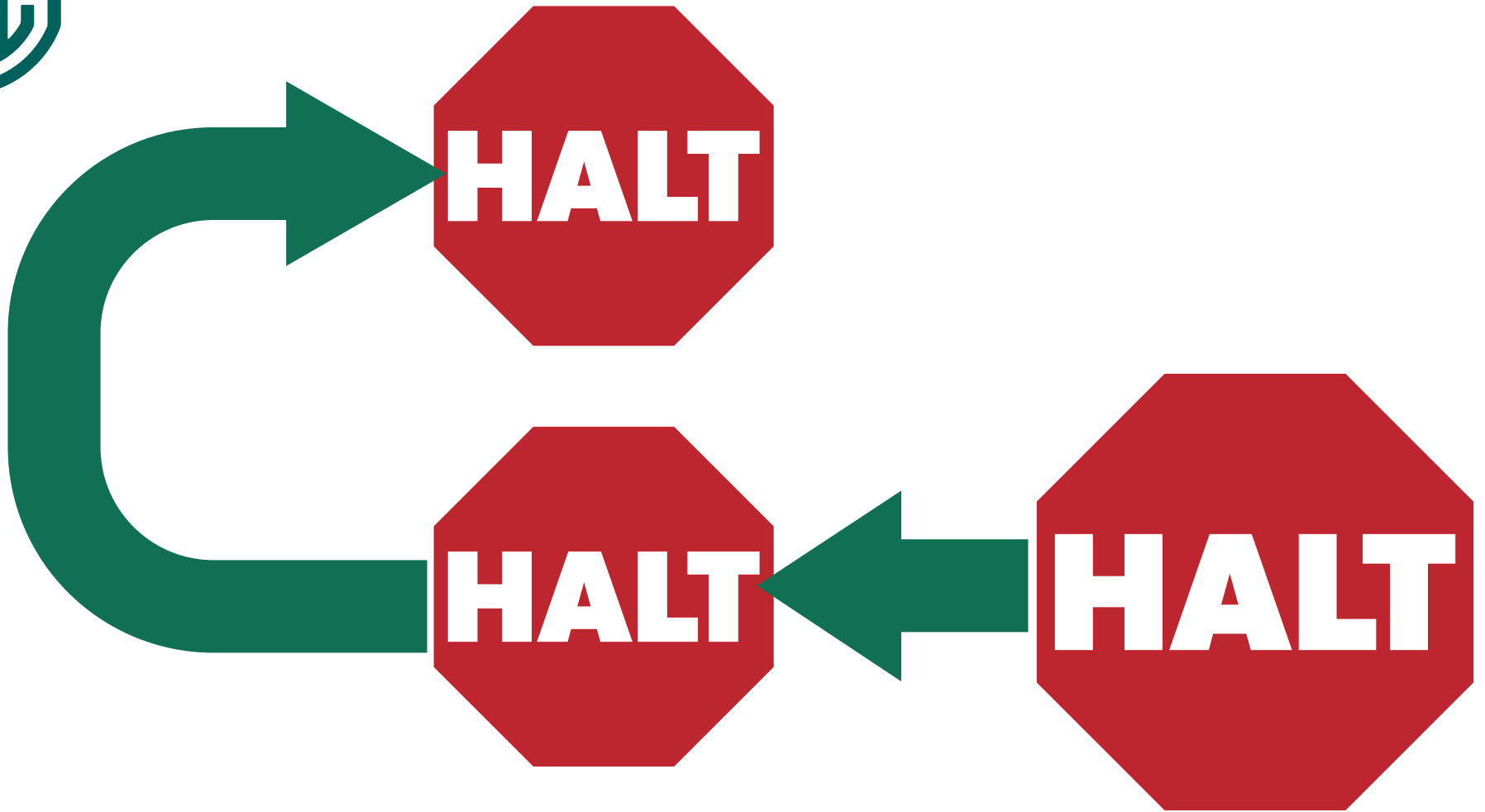
HALT
Leave,
Call Dog
Over Jump,
Front,
Finish Right



**HALT
Leave,
Call Dog
Over Jump,
Front,
Finish Left**



**HALT - 90° Pivot Right,
HALT 180° Pivot Left - HALT**



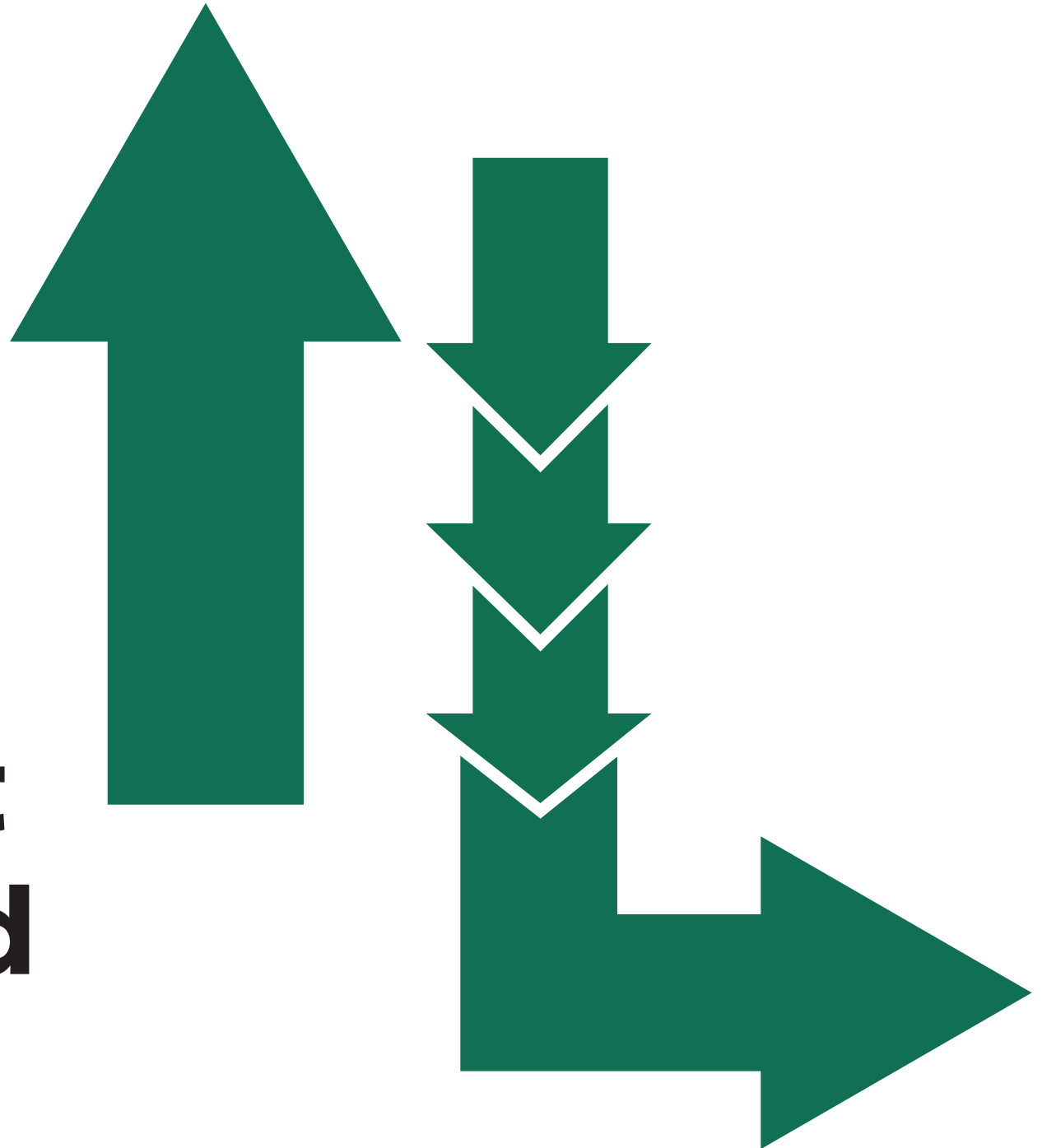
**HALT - 90° Pivot Left,
HALT 180° Pivot Right - HALT**



**Forward,
Reverse
3 Steps,
Pivot
90° Left
& Forward**

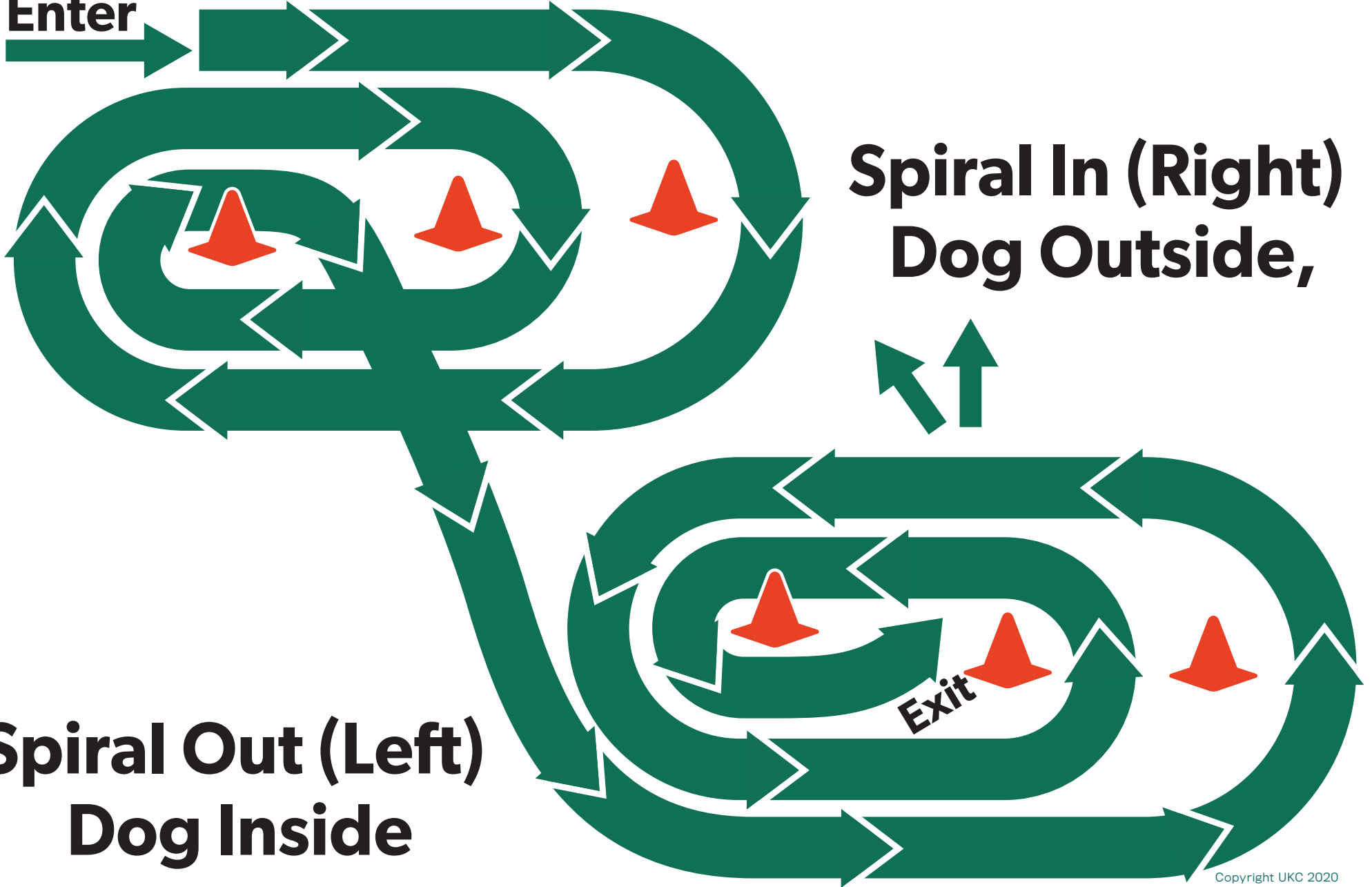


**Forward,
Reverse
3 Steps,
Pivot
90° Right
& Forward**



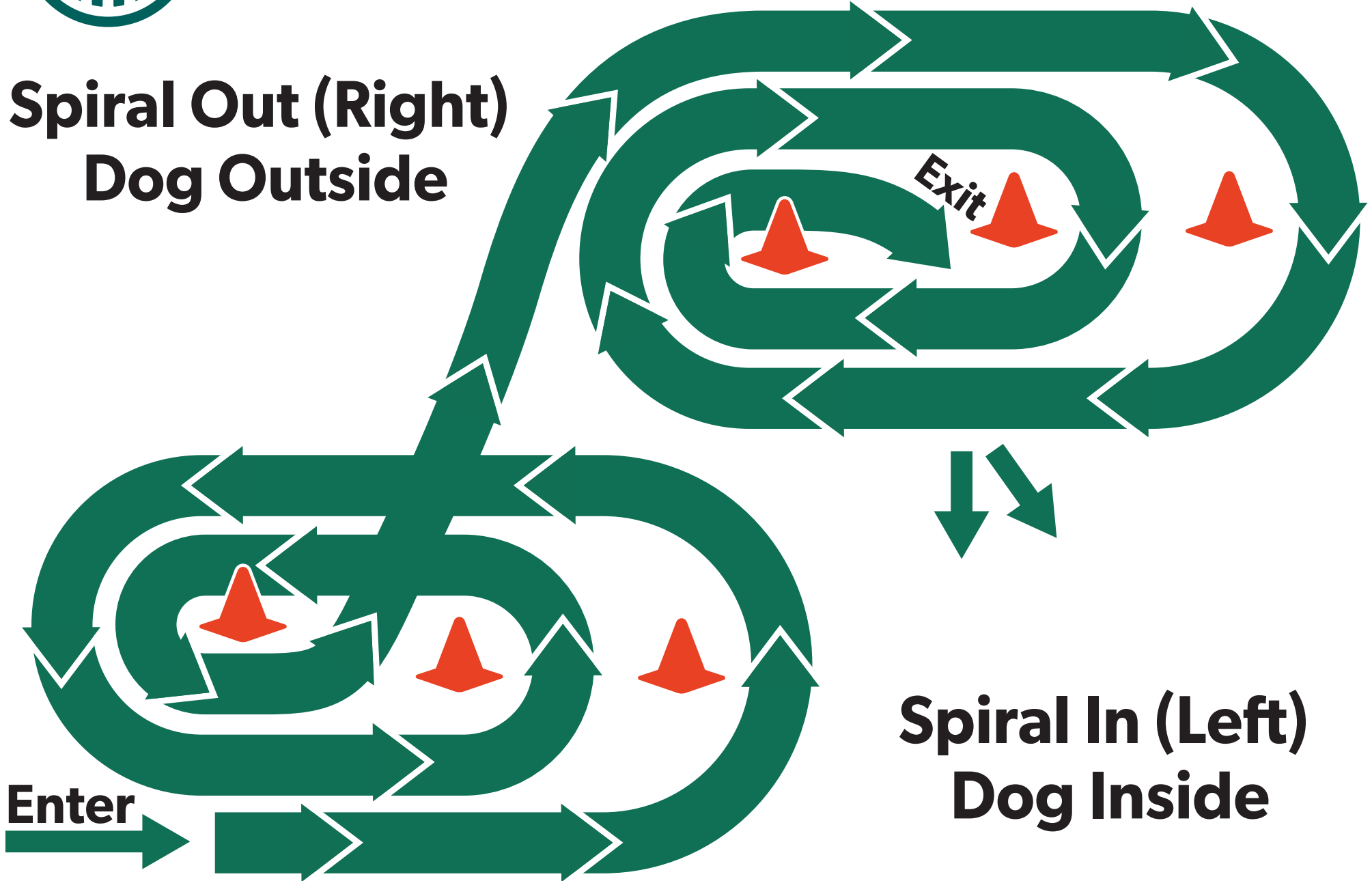


Enter

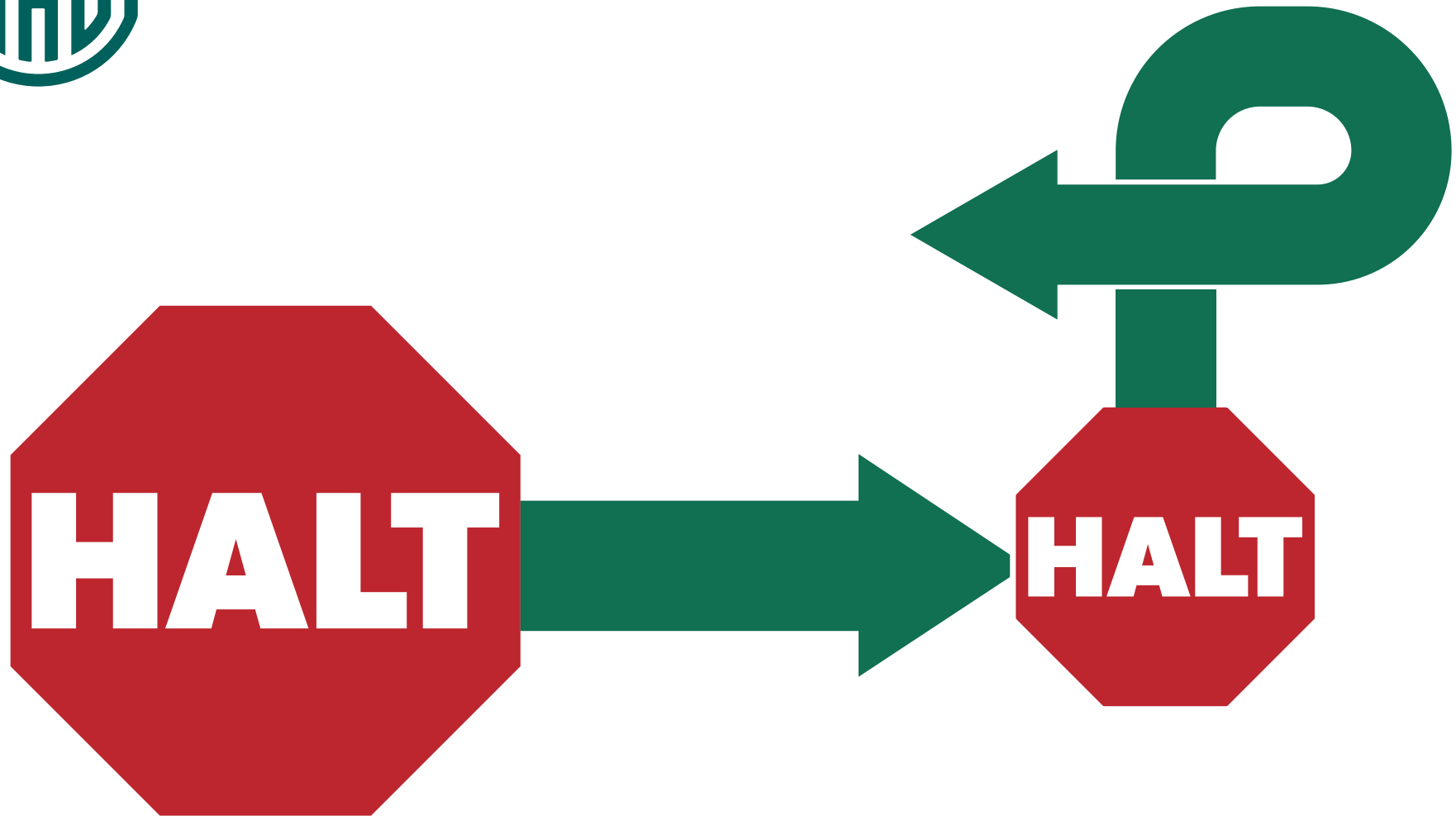




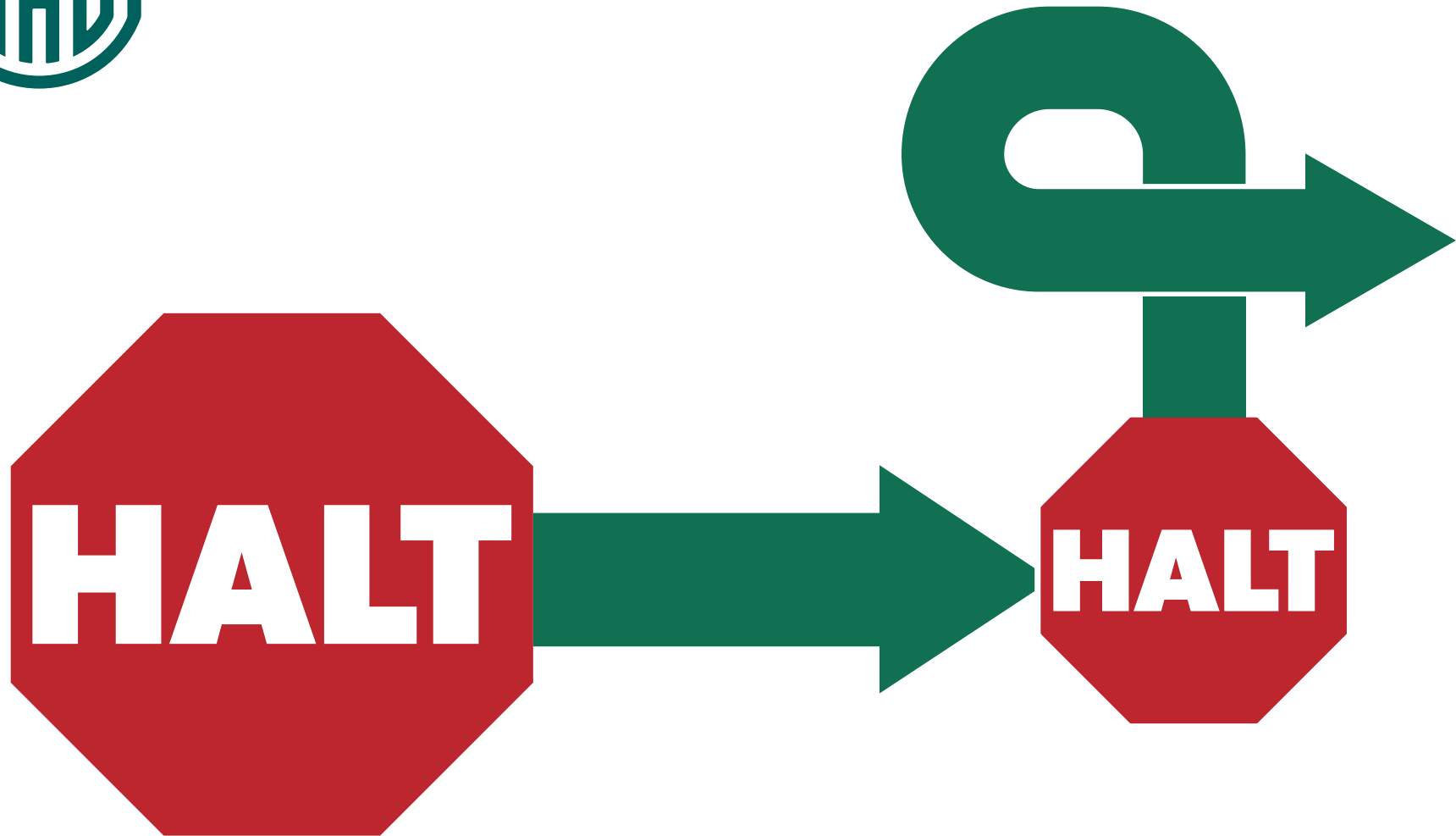
**Spiral Out (Right)
Dog Outside**



**Spiral In (Left)
Dog Inside**



**HALT - Side Step Right, HALT
270° Right Turn & Forward**



**HALT - Side Step Right, HALT
270° Left Turn & Forward**



**Moving Stand,
Walk to Cone,
HALT
Call Dog
to Heel**

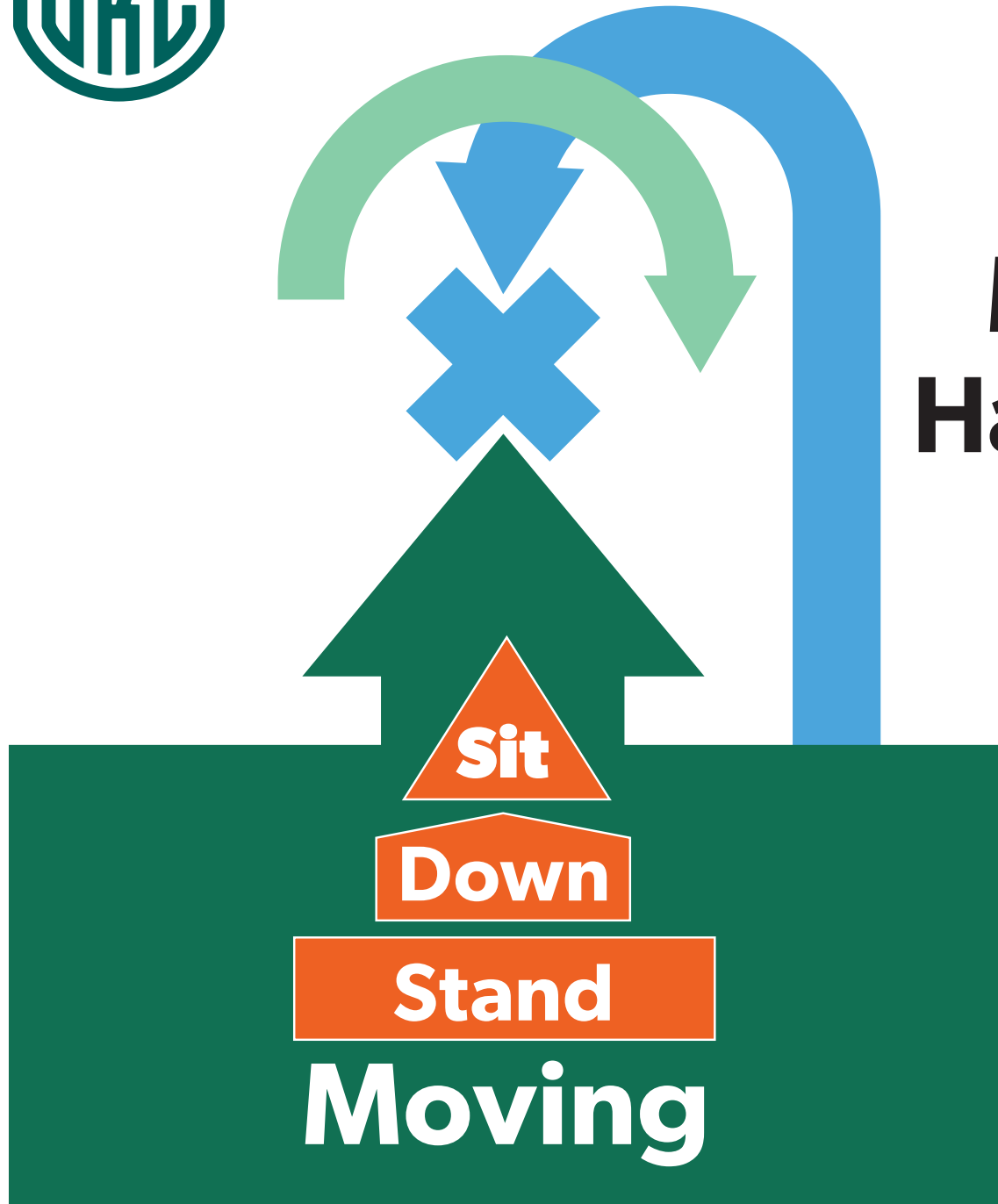


**Moving Sit,
Walk to Cone,
HALT
Call Dog
to Heel**

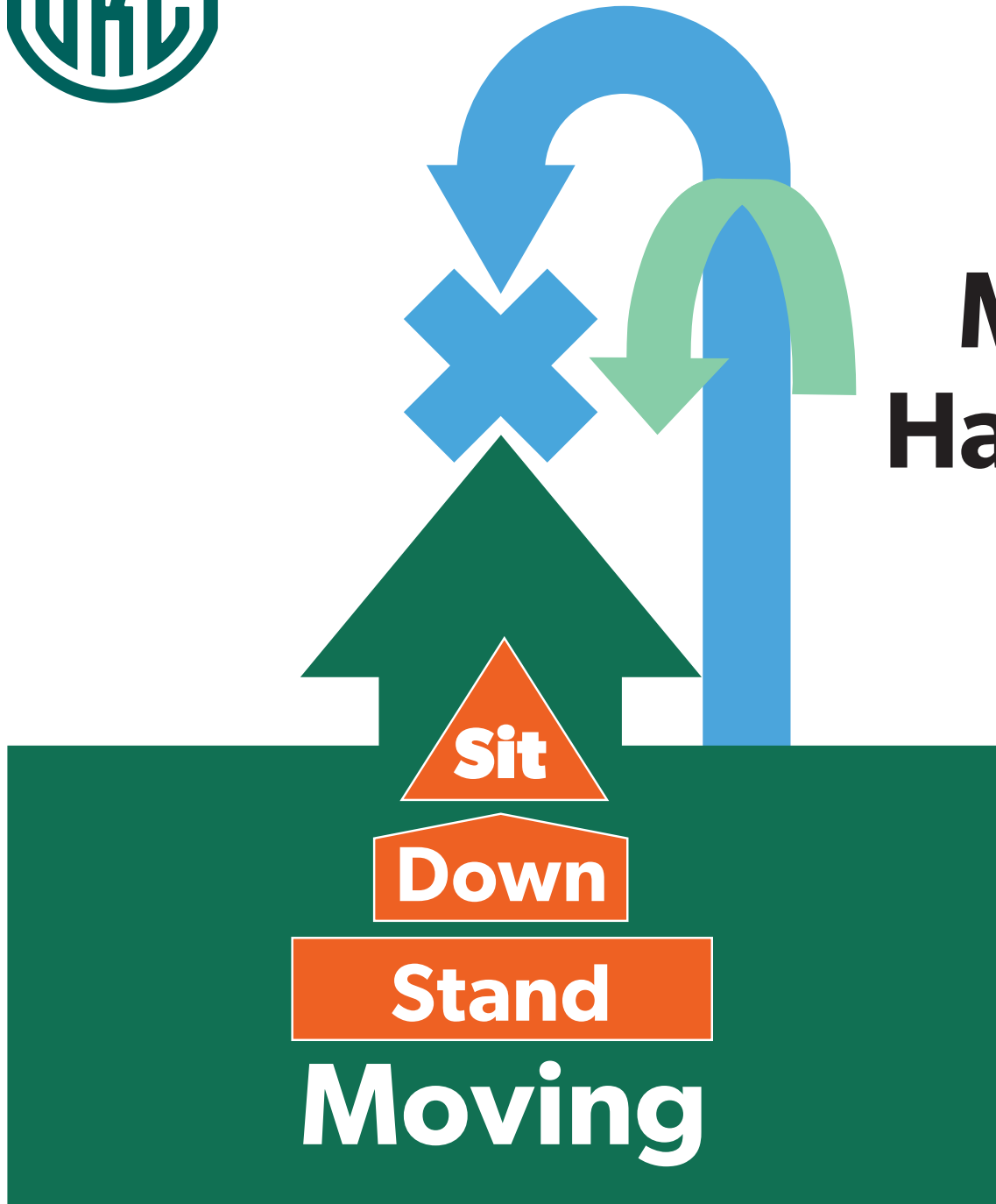


**Moving Down,
Walk to Cone,
HALT
Call Dog
to Heel**

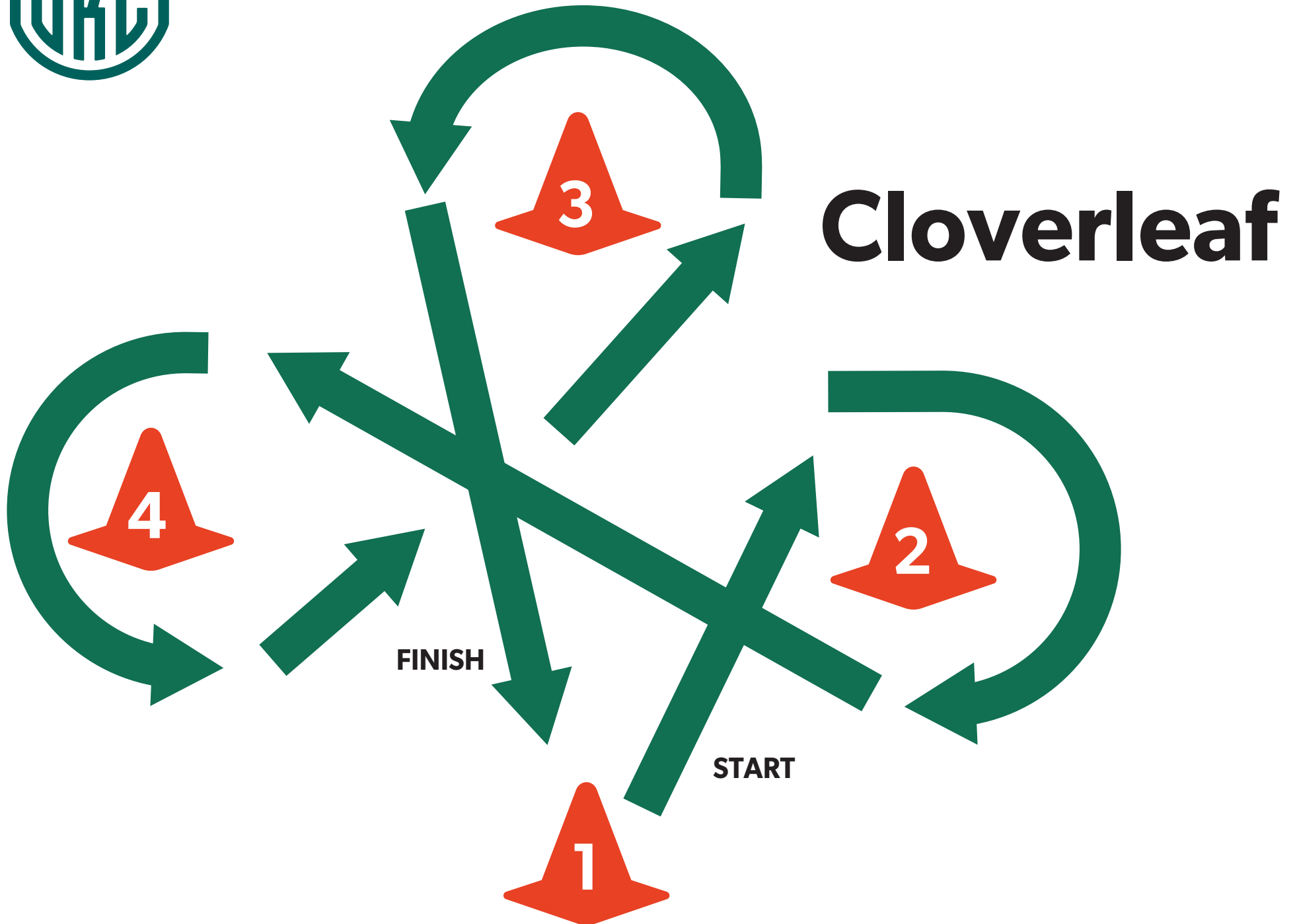


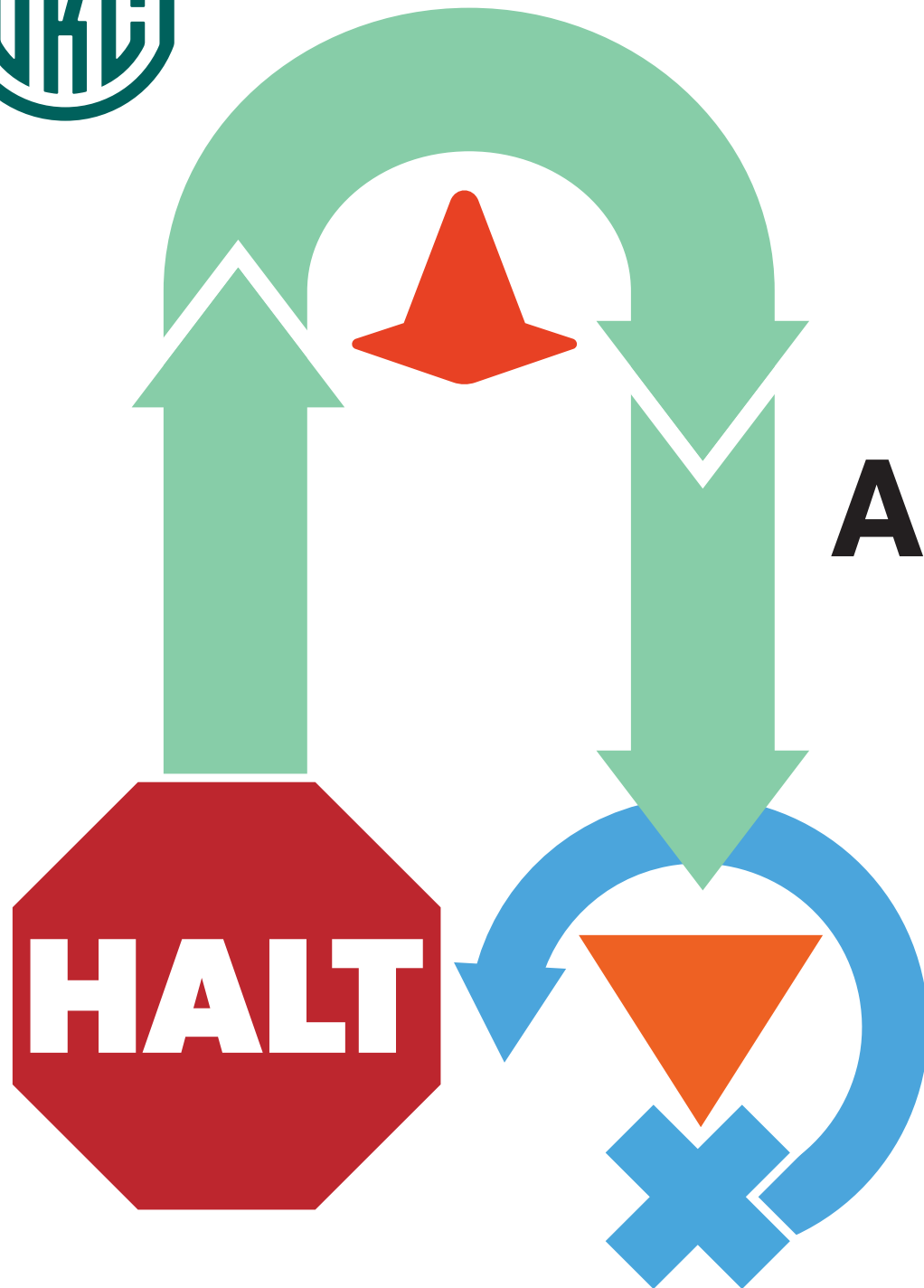


**Moving Stand,
Handler Forward,
Face Dog,
Dog Down,
Dog Sit,
Finish Right**



**Moving Stand,
Handler Forward,
Face Dog,
Dog Down,
Dog Sit,
Finish Left**





**HALT
Send Dog
Around Cone,
Dog Front,
Handler
Returns
Right**



HALT
Send Dog
Around Cone,
Front, Finish
Right 180°
Pivot Right
Forward



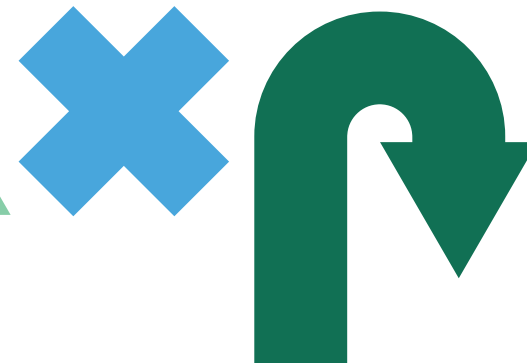
HALT
Send Dog
Around Cone,
Front, Finish
Left, 180°
Pivot Right,
Forward

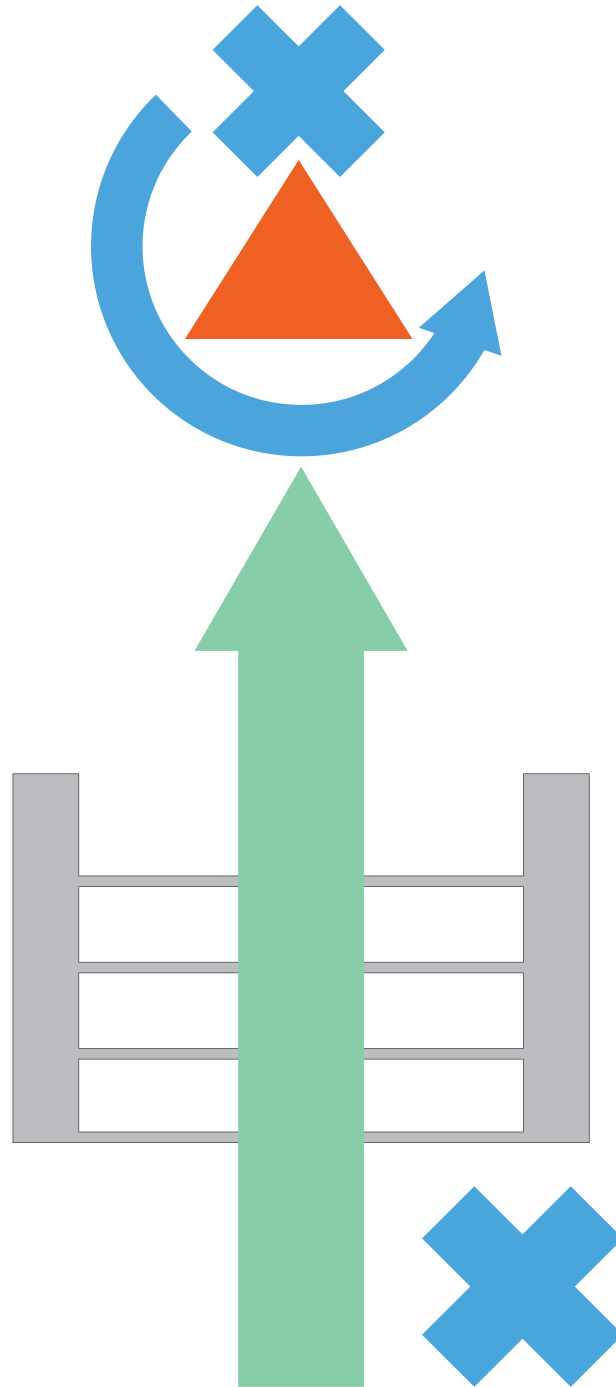


HALT
Send Dog
Around Cone,
Return to Heel
Right, 180°
Pivot Right,
Forward



**HALT
Send Dog
Around Cone,
Return to Heel Left,
180° Pivot Right
& Forward**





HALT
Leave Dog,
Call Dog
Over Jump,
Dog Front,
Handler
Returns
Right